Approved FarRelease 2004/07/29 : CIA-RDP78B047 A000200010054-1

19 July 1967

PLEASE ACKNOWLEDGE RECEIPT FOR THE MATERIAL LISTED BELOW:

Ltr-June Progress Report Cys 3, 4, and 5 of 7 cys

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Subject: June Progress Report,

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In the study of Distortion Feedback Servo Loop Stability, approximately 32 percent of the work is completed; while on the Registration Correction Accuracy Program, approximately 45 percent of the work is completed.

Image Dissector Scan Distortion is approximately 95 percent complete. =42%

Technical Progress: The program to close the servo loop to eliminate displacement, scale and skew errors was written and debugged. Several preliminary tests were made on raster size, spot size and intensity to determine optimum combinations for maximum pull-in range.

> Initially the program was written to cause X and Y displacement to be reduced first and then to operate on scale and skew errors. This subroutine was rewritten so that all errors are reduced simultaneously, as will be done in the hardware system.

Several subroutines have been added to ease the operator input task and facilitate an intensive testing phase. The display subroutine has been changed to show graphically, the error reductions.

25X1

The test photographic plates were evaluated by comparison against known standard samples and could be described as 30 line/mm material, except at the corners; the original camera Duplicate copies of identical and stereo plates were examined under both maximum and minimum zoom conditions. In each case three conditions of parallax clearance were investigated

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- 1.2.1 Open Loop: Operator clears parallaxes on floating mark manually only with no electronics on and without moving plate between readings to determine accuracy of observation means.
- 1.2.2 Closed Loop: Operator clears parallaxes on floating mark with correlator operating, but without moving plate in between readings to determine accuracy of observation with servo disturbances included.
- 1.2.3 Closed Loop Plus Transport: Operator clears parallaxes on floating mark with correlator operating and moves plate in between readings to determine accuracy of automatic parallax clearance.

There was little difference between all of these cases, the standard deviation of parallax clearance referred to plate coordinates ranged between 2 and 4×10^{-4} inches (5 and 10 microns), and was considerably better in some cases. Since the differences between the various experimental conditions were so slight, it indicates that the correlation circuitry is operating nearly as well as the human operator in removing parallaxes from the model.

1.3 Image Dissector Scan D	istortion; Electronic distortion of the
scanning raster has been inco	rporated in the video-correlation
breadboard for	and will be included in the final system.
Part of this effort was done un	nder
To date the circuits for	modulating the deflection wave forms
have been designed and built,	and the distorted deflections (manually
controlled) have been applied	to the image dissector tubes. The

Next Month:

testing will be carried out under

Servo toop Stability

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2.1 An intensive test phase will be started to determine maximum pull-in ranges for each type of distortion, and the limits on distortions when all are present simultaneously. Investigations on feedback parameters as they affect pull-in will be conducted. The elimination of peak and valley count as a feedback parameter will be investigated. All of the above tests will be made for a variety of images and densities.

distorted rasters have been observed with a monitor scope. Further

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Registration	the apparatus (zoom land quality) which will will be prepared and	lens focus adjustm Il be corrected nex the position of the	some minor deficiencies is ent, floating mark illumin t month. A detailed test floating mark on the scan ed. Final tests will then	ation plan
Scan Distortican 25X1	insofar as they are co		eported under schedule; that d later than is scheduled to	
			Sincerely,	
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			Project Manager	
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